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6 MN Force Calibration Machine

Hydraulic Amplification Upgrades

Section C: EC&I Upgrades & Integration

Technical Specification

Project Reference: FL2018-P001

Table of Contents

1 Project Background

1.1 The Metrology Institute

The National Metrology Institute of South Africa (NMISA) is responsible for maintaining the S.I. units and to develop primary scientific standards of physical quantities for South Africa. The NMISA maintains and compares those standards with other national standards to ensure global measurement equivalence. It must also provide reference analysis in the case of a measurement dispute. The NMISA also maintains and develops primary methods for chemical analysis for the purposes of certifying chemical, electromagnetic and physical references.

1.2 Force Calibration Services

The NMISA Force Laboratory is responsible for the international traceability of force measurement in South Africa. To this end, the institute maintains and operates a hydraulically amplified, Deadweight Force Calibration Machine. The machine itself is over 40 years old and its hydraulics are in need of modernization.

2 Machine Description

2.1 Current equipment

The machine is comprised of two inter-dependent sections; a deadweight lifting section (which has recently been renovated) and a hydraulic section consisting of three hydraulic presses.

The *Deadweight Section* consists of the following major components and ancillaries:

- Deadweight Lift Motor: 4.0 kW (380 VAC/3-phase), 11.0 A Servo Motor
- Platform Motor: 160 W (230 VAC), 3.0 A Servo Motor
- 2x Electro-magnetic brakes
- Hydrostatic bearing motor: 0.5 kW (240 VAC)
- Tare beam motor: 160 W (230 VDC), 3.4 A Servo Motor
- Allen-Bradley CompactLogix PLC
- Stratix 2000 unmanaged ethernet switch
- 10” Allen Bradley Panelview Plus 7 HMI

The *Hydraulic Section* is driven by a *hydraulic power pack* (**HPU**) with the following motors:

- 3.8 kW (380 VAC)
- 7.5 kW (380 VAC)
- 2x 0.37 kW (380 VAC)
- 3x 1.1 kW (380 VAC)

The HPU is to be replaced with a new and modern model of similar or lower power demands. The said HPU replacement must be a self-contained unit with its own control panel that will communicate with the existing machine control panel.

2.2 Force Traceability Process

The existing *Deadweight Section* generates force by means of a stack of calibrated stainless-steel mass pieces. The applied force pulls upon the deadweight cradle, which in turn applies this force (F_0) upon the deadweight loading piston. A balancing pressure (P_0) is thus developed within the deadweight loading piston. This balancing pressure is then transferred to the piston cylinder in each of the three force presses. Each piston cylinder has a specific cross-sectional area; it is in this way that the deadweight force is amplified to 200 kN (F_1), 1000 kN (F_2) and 6000 kN (F_3) of applied force respectively. The transmission ratios are as follows:

- *200* kN *force Standard Machine (F_0 to F_1) – 1:5*
- *1000* kN *force Standard Machine (F_0 to F_2) – 1:25*
- *6000* kN *force Standard Machine (F_0 to F_3) – 1:150*

For these ratios to be achieved and for the traceability chain to remain unbroken, the balancing pressure (P_0) needs to be exactly equal to the piston cylinder pressure (P_1; P_2; P_3) respectively. This process is illustrated in *Figure 1* in the appendix below.

The accuracy to which these pressures can be balanced has a major bearing on the uncertainty of measurement of the force amplification. Therefore, it is required of the HPU to both generate and maintain the needed pressure in the deadweight loading piston and the respective piston cylinders to high accuracy and precision. Force calibrations are taken at each force interval. Each force value must be generated and maintained stable for 30 seconds.

	Pressure Range (MPa)		Stability Range
Force (kN)	Min	Max	kPa
200	2	25.5	6
1000	1.9	25.4	12
6000	2.2	29.1	21

The piston cylinders of each of the three force presses are positioned on three column frames. Each loading frame connects to the respective pistons by means of a spherical hydrostatic bearing. Thus, axial support is provided with minimum friction and misalignment

The vertical position of the piston is supported by means of eight horizontal hydrostatic bearings; four at the upper and four at the lower end of the piston cylinder. This ensures that the gap between cylinder and piston is kept as small as possible without the rotation of the piston being hampered.

These hydrostatic bearings are to be independently pressurized by the HPU. The pressure feed will need to be modulated and monitored continuously. A spike in this pressure would indicate that the nozzles of the bearing feed jets are blocked. The HPU's control system would need to flag an alarm and initiate pressure safety protocols. This process for each piston cylinder is illustrated in *Figure 2* in the appendix below.

The force calibration cycle requires multiple iterations of force generation (and by extension, pressure generation) to specific values. As a result of each calibration run, the viscosity of the hydraulic fluid fluctuates as a result of the inherent temperature fluctuation. Consequently, the temperature of the hydraulic fluid needs to be maintained within acceptable limits. The existing Hydraulic Power Pack (***HPU***) has fallen into disrepair and needs to be upgraded or replaced.

3 Proposal Requirements

The EC&I of the *Deadweight Section* (*DW Section*) of the machine was recently upgraded. It controls the movement of the mass pieces and the calibration of loadcells using the stainless-steel mass pieces. It is essentially the heart of the machine and the soon-to-be – procured HPU operates in service of the *DW Section* (refer to *Figure 1* in the *Appendix*).

The HPU will be installed with a self-contained control panel or have the required EC&I equipment built into the existing Main Control Panel. This will be discussed during the site meeting and at the project's contract phase.

3.1 Upgrade of Hydraulics' EC&I and Integration with Existing Deadweight Control Panel

3.1.1 Updated field instruments

The Hydraulically Amplified Force Calibration Machine is a high precision, high accuracy machine. As such, each *Hydraulic Press* is fitted with several field instruments that provide real-time feedback on position and condition. The current field instruments are faulty, in disrepair or obsolete. These will need to be replaced.

The said instruments are as follows:

- *Hydraulic Cylinders:*
    - *Level transducers/Travel transducers*
    - *Limit Switches*
    - *Hydrostatic bearing motors*
    - *Loadcell platform motors*
    - *Cylinder draining pumps*
- *Pipework Instruments*
    - *Fluid flow meter (local flow indicator would be acceptable upon discussion)*
    - *Pressure Transducers*
    - *Temperature transducers*
    - *Motorized valves (where applicable)*
    - *Flow modulating valves*
    - *Shut-off valves & Relief valves*

- *The following table depicts the expected field instrument placements:*

Field Instrument	Pressure Transducers	Pressure Indicator	Temperature Transducers	Temperature Indicator	Fluid Flow Sensor	Fluid Flow Indicator
HPU delivery	*	*	*	*	*	Optional
HPU Return Line	*					
Piston Cylinder Inlets	*	*	Optional	*	*	*
Piston Cylinder Return lines	*					
Hydraulic Jet Nozzle inlets	Optional	*				Optional

3.1.2 EC&I Integration

The EC&I of the *Deadweight Section* (*DW Section*) was recently upgraded. All instruments and equipment installed in the *Hydraulic Section* will need to be integrated with the existing control panel, such that all functions of the machine can be controlled from the existing HMI.

This will necessitate some EC&I upgrades and installation which include, but not limited, to the following:

- *Extended Control Panel (where applicable)*
- *Comms cabling, instrument cabling and power cabling to and from the control panel (with appropriate trunking)*
- *Isolators to all motors*
- *Power supply cable and glands*
- *Updating the existing Allen-Bradley HMI & PLC to accommodate newly installed instruments and equipment (as described by this document)*
- *Updating of real-time monitoring and feedback system*
- *Integrating communication with installed HPU and field instruments*

This portion of the works requires considerable coordination with *the planned installation of a Replacement Hydraulic Power Pack and its associated control panel & equipment.* Bidders will need to specify the expected communications, I/O's and wiring terminals configuration required from the HPU.

During the contract stage, NMISA will organize a project kick-off meeting where the EC&I integration details can be planned coordinated. Further details will be discussed during the site visit. Any additional technical queries should be sent to NMISA in writing via email.

3.1.3 System Software Competences

- *Licensed PLC & HMI Software (where applicable)*
- *End User programmable system parameters*
- *Data monitoring and capture*

3.1.4 Ancillaries

- *Labour:*
    - *Installation on NMISA premises*
    - *Software installation & training*
    - *Commissioning of equipment and training of NMISA personnel*
    - *Removal of old instruments, cabling and racks*
    - *Installation of appropriate panels, cabling and racks*
- *Operating Manuals*
- *Cable schedules*
- *Equipment list & Load list*
- *Panel wiring schedules*
- *Critical spares list*

Note:

- *Any deviations from the above scope should be explicitly stated. A succinct description of the deviation and the reasons thereof should also be included.*

4 Additional Information and Documentation

4.1 Technical documentation

Kindly refer to the accompanying documents:

- *Equipment flow chart.*
- *Photographs of the machine*
- *Existing EC&I equipment (list can be obtained during the site visit)*
- *GA & P&ID Drawings of Hydraulic Presses (can be viewed during the site visit)*
- *Draft FDS (can be obtained upon email request by bidders)*

4.2 Lab Environment

The following site conditions shall be taken into consideration in the design of the equipment:

- Altitude above sea level: approximately 1330 m above sea level
- Ambient Temperature: 19-22 °C
- Ambient Relative Humidity: 35-55 %
- The application is in a manned indoor laboratory.
- Available Power supply:
    - single phase 230 VAC
    - three phase 400 VAC
    - 100 A current supply

4.3 Proposal Documents & Requirements

4.3.1 Site Visit

It is highly recommended that a site visit be organised with the NMISA Force laboratory staff in order to better ascertain the HPU requirements and installation conditions. Bidders are to request a site visit by email at their earliest convenience. Kindly refer to the bid document for further details.

4.3.2 Schedule of Previous Works

The supplier shall demonstrate prior competence in similar applications. A schedule of previous works is to be attached to the supplier's submission. Each reference should include the following:

- *Brief description of reference*
- *Value of reference work*
- *Location of reference work*
- *Contact details of reference (or to be readily available upon request by the NMISA)*

4.3.3 Completion of works

The supplier shall successfully demonstrate the following to the Engineer prior to the commissioning and acceptance of the Works:

- *Equipment operation.*
- *Achievement of the specified performance requirements*
- *Control system operation (where applicable)*
- *Operation of all safety devices*

4.3.4 Guarantees

The supplier shall indemnify the NMISA against any factory defect or deficiency of workmanship. The supplier is to provide a defect guarantee or warranty for the supplied equipment.

A claim shall be lodged with the supplier for defects in the material, equipment or workmanship that render the Hydraulic Power Pack incapable of performing adequately to the specified performance expectations during the guarantee period. The supplier shall, as soon as possible after receipt of the claim, take the necessary steps to enact repairs or replacements as necessary. This is subject to the goods having been treated with reasonable care, in accordance with the supplier's operating manual.

4.3.5 Safety Requirements

The supplier, their goods and their craftmanship, shall comply with accepted industry safety regulations (e.g. the OHS Act No. 85 of 1993; Amendment Act No 181 of 1993; OHS Act 2009 Amendment: Pressure Equipment Regulation; OHS Act No. 85 of 1993: Driven Machinery Regulations etc.) and associated regulations.

The supplier shall provide a comprehensive health and safety plan upon supply and/or commissioning of the equipment.

All works are to be in accordance to *SABS ISO 9001:2015*

4.3.6 Additional requirements

Kindly refer to the NMISA procurement requirements, terms and conditions as stipulated in the Bid Document (*ToR document*) and the NMISA SCM tender documentation and/or the specified location on the NMISA online repository.

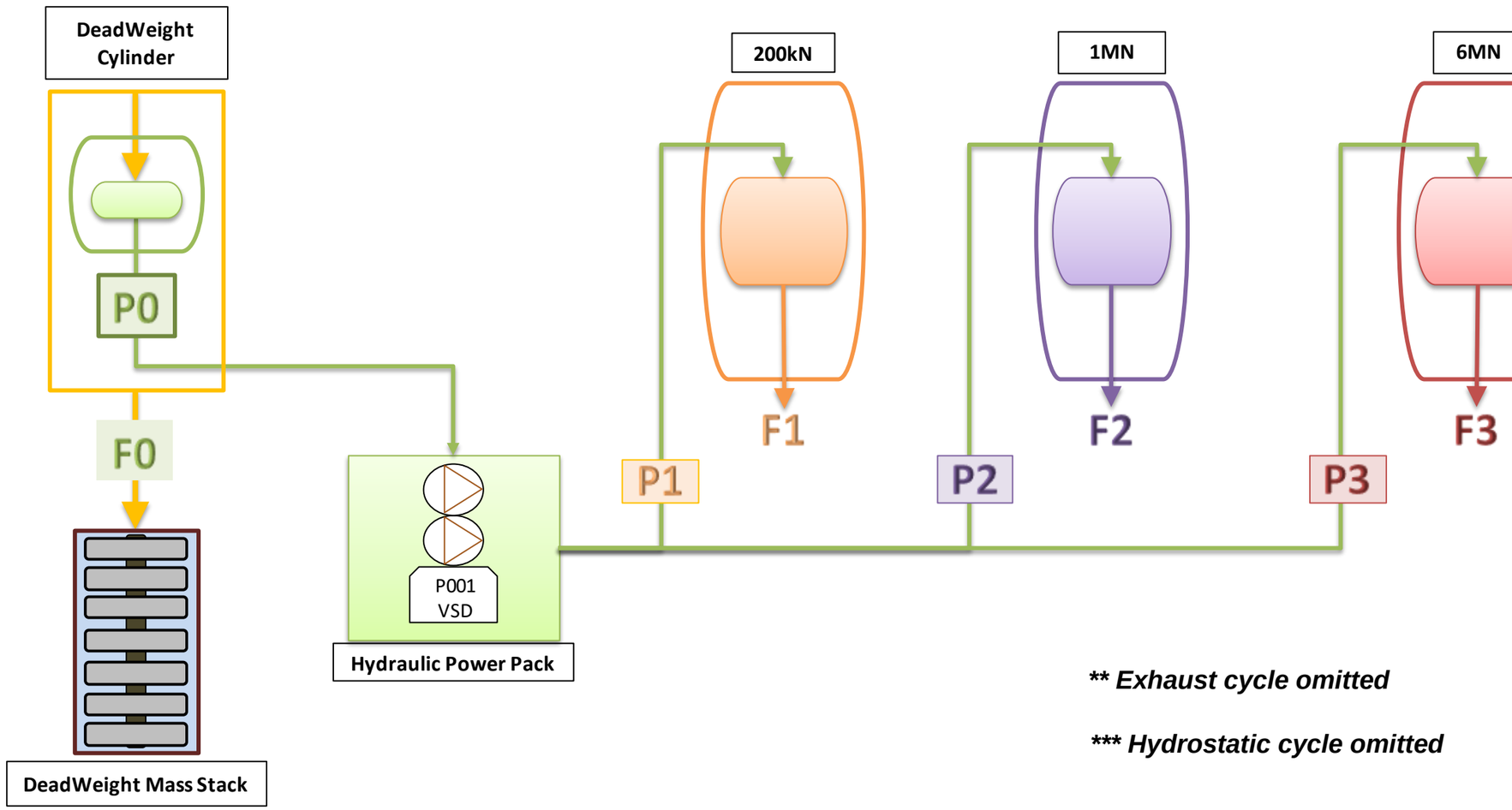
5 Appendix

5.1 Process Flow Diagrams

PROCESS FLOW DIAGRAM

Department: Force & Torque
Client: Force & Torque
Project Number: FL2018-P001

Section: Force & Torque
Date: Thursday, 12 March 2020
Revision: A



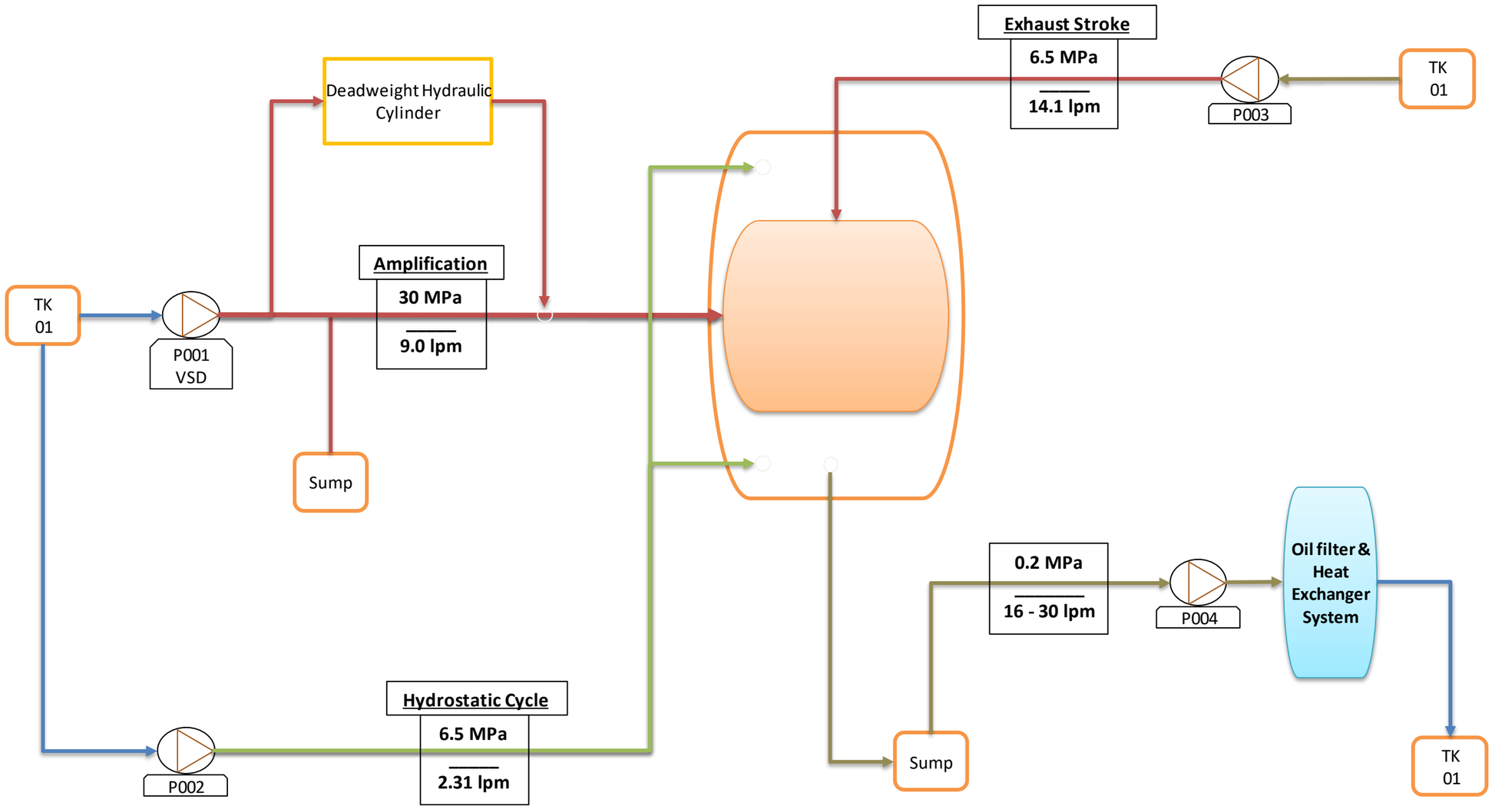
		Name	Date	Rev	Issued for:
Comments:	Hydraulic Amplification Force Machine : Hydraulic Transfer of Deadweight Force	**Designed:**	Mbuso Sibisi	Wednesday, 25 March 2020		RFQ
		Checked:				
		Approved:				

Figure 1 - Pressure Transfer Diagram

PROCESS FLOW DIAGRAM

Department: Force & Torque
Client: Force & Torque
Project Number: FL2018-P001

Section: Force & Torque
Date: Thursday, 12 March 2020
Revision: A



Comments:	Hydraulic Amplification Force Machine: Hydraulic Circuit – 6MN Force Press (All pressure values are nominal values during operation)		**Name**	**Date**	**Rev**	**Issued for:**
		Designed:	Mbuso Sibisi	Thursday, 12 March 2020		RFQ
		Checked:				
		Approved:				

Figure 2 - 6 MN Hydraulic Press PFD

5.2 Machine Photographs

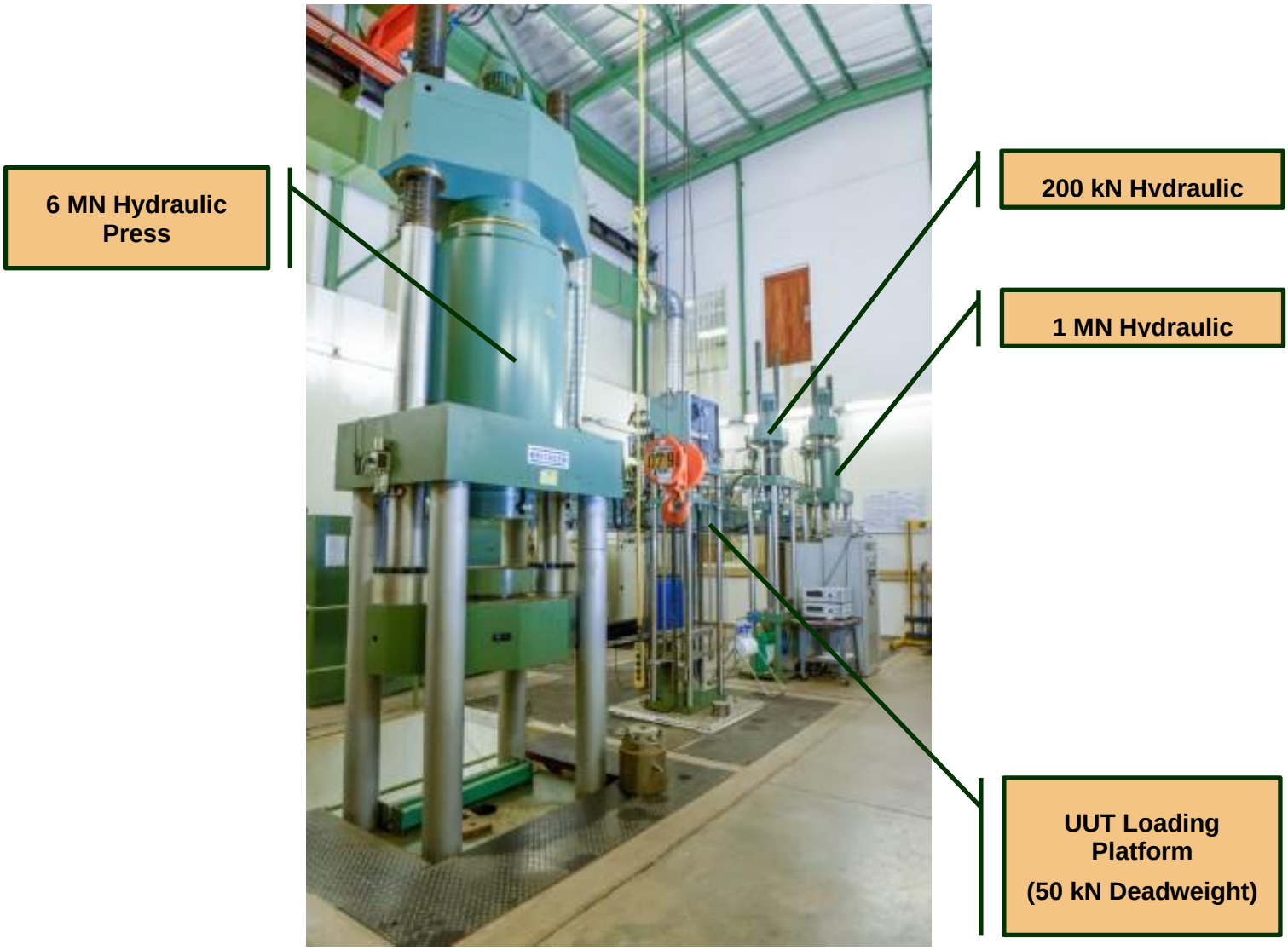


Figure 3 – Hydraulic Presses

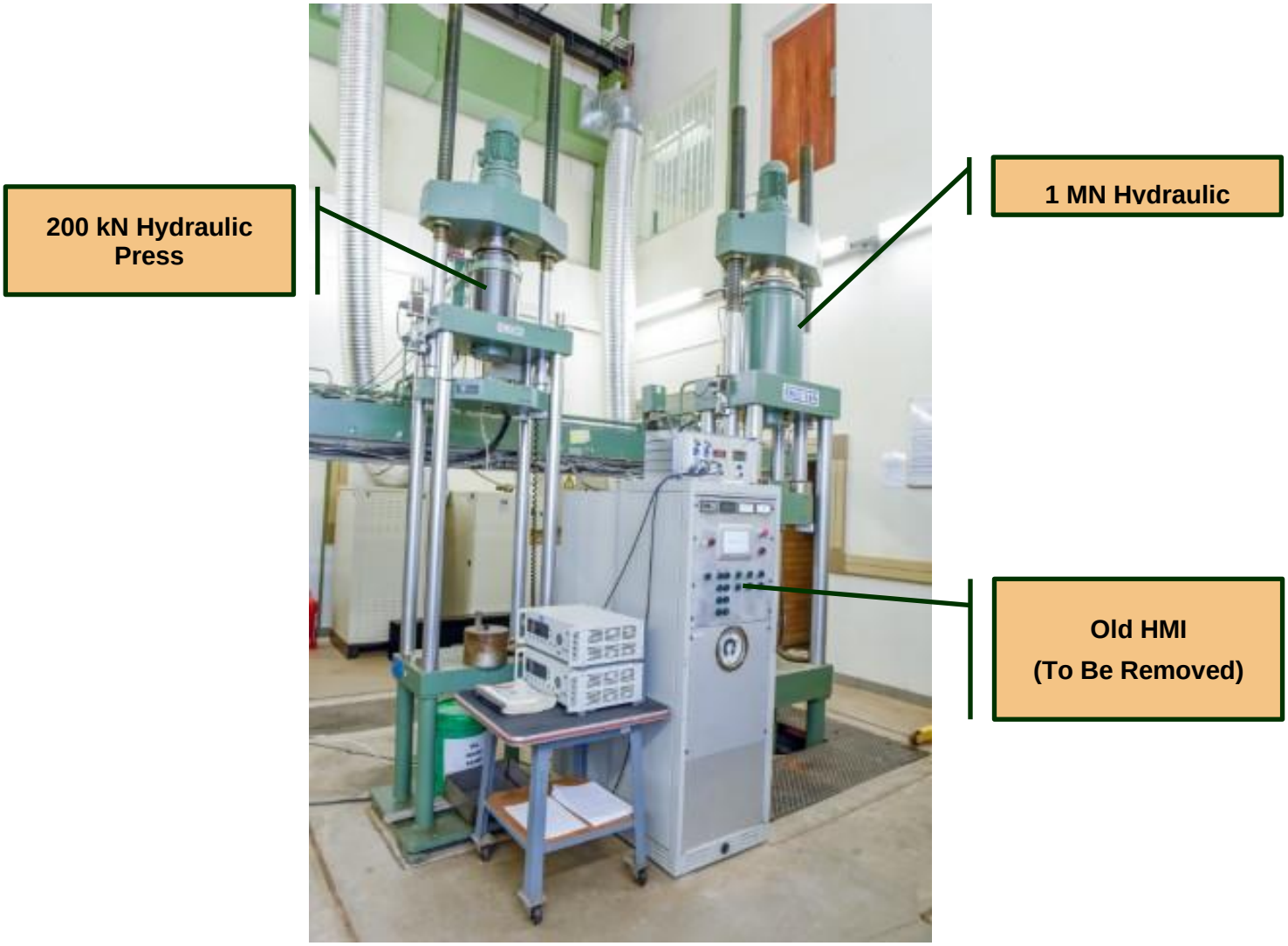


Figure 4 – Force Presses

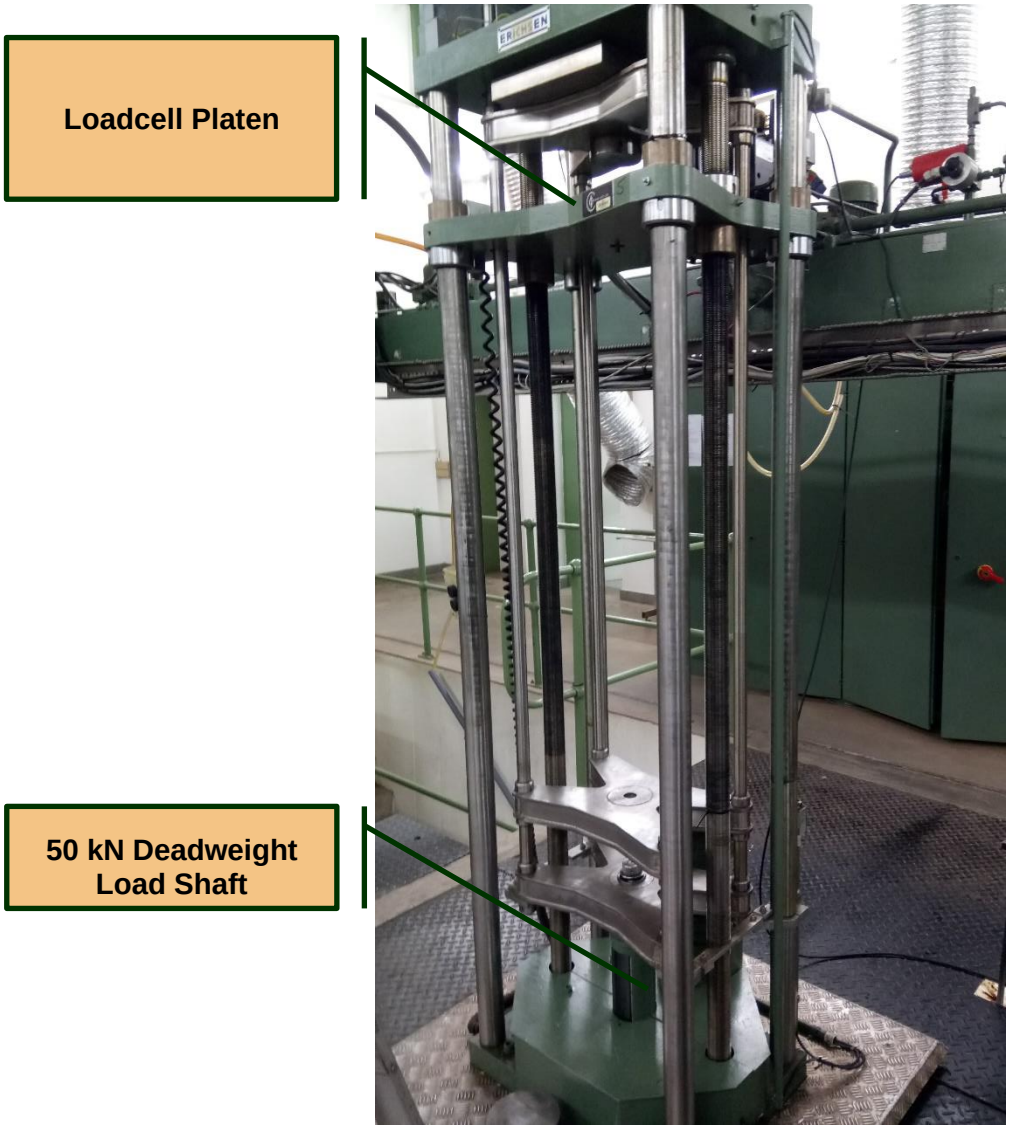


Figure 5 - UUT Loading Platform

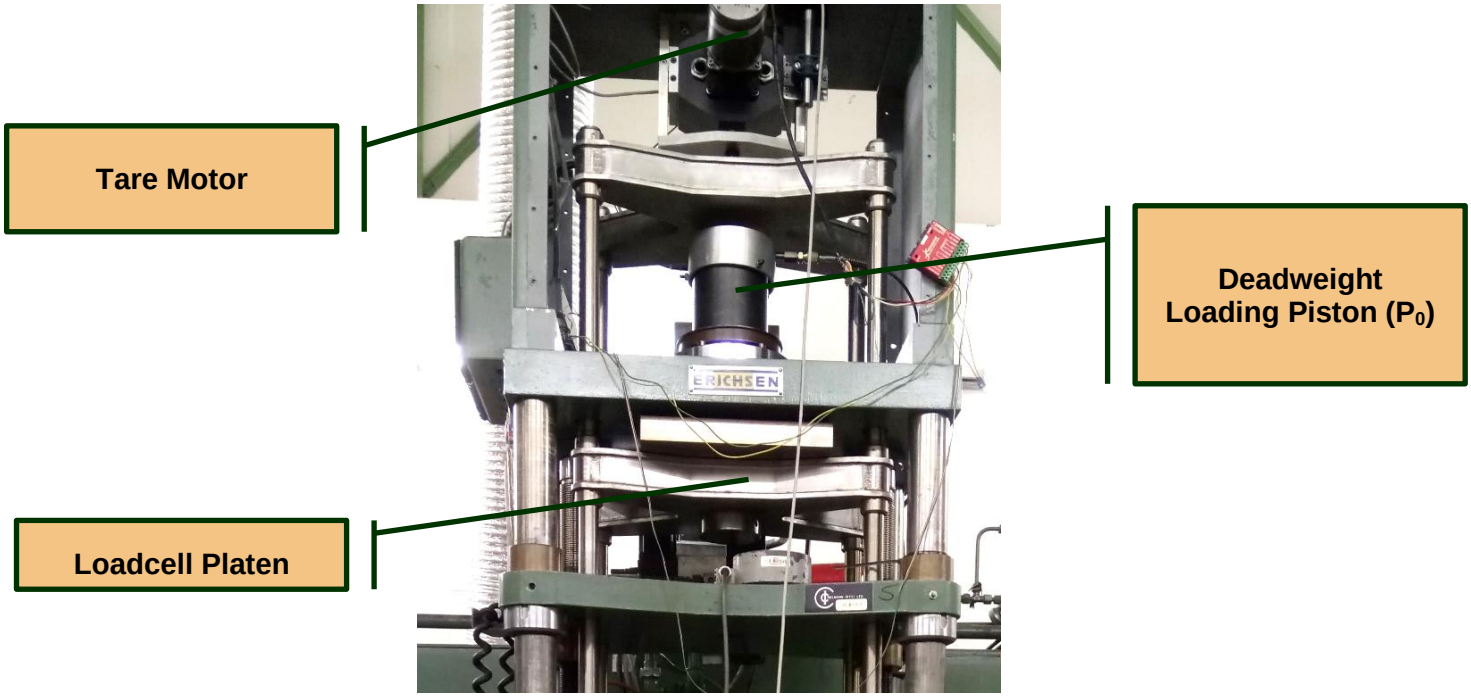


Figure 6 - Taring System

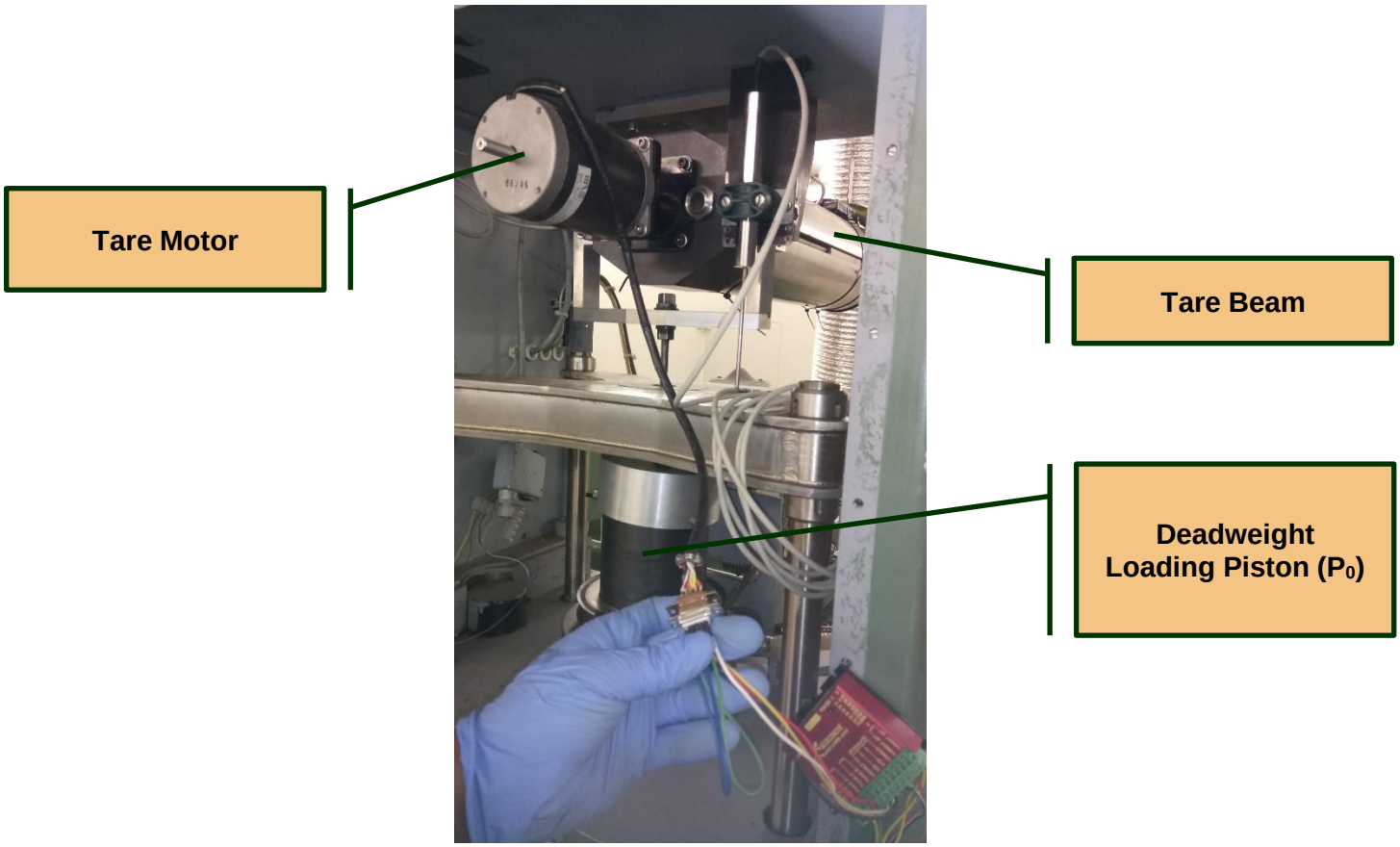


Figure 7 - Tare Beam

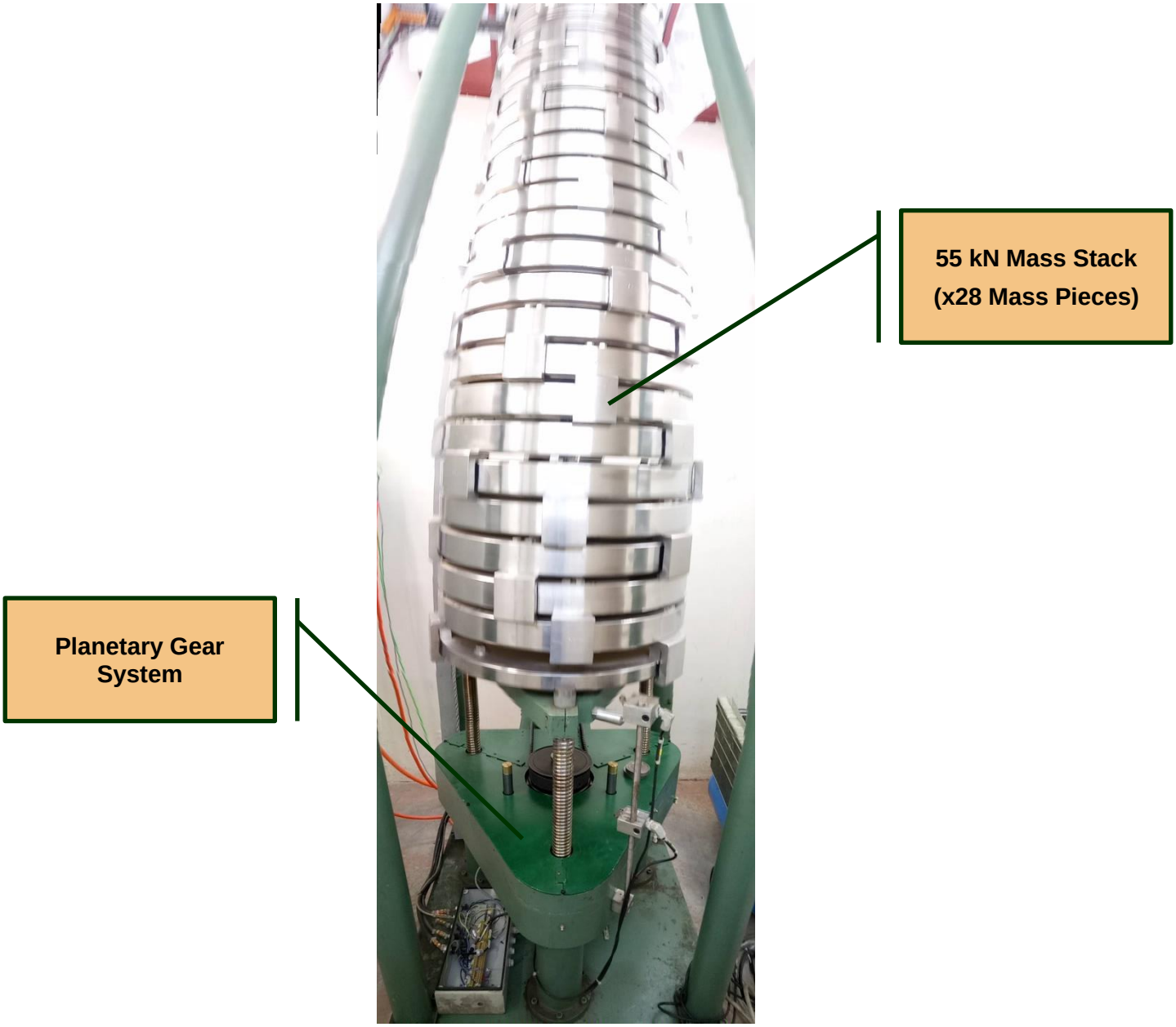


Figure 8 - Mass Piece Section

Figure 9 - 1MN Force Press

Figure 10 - Existing HPU valve block & instruments

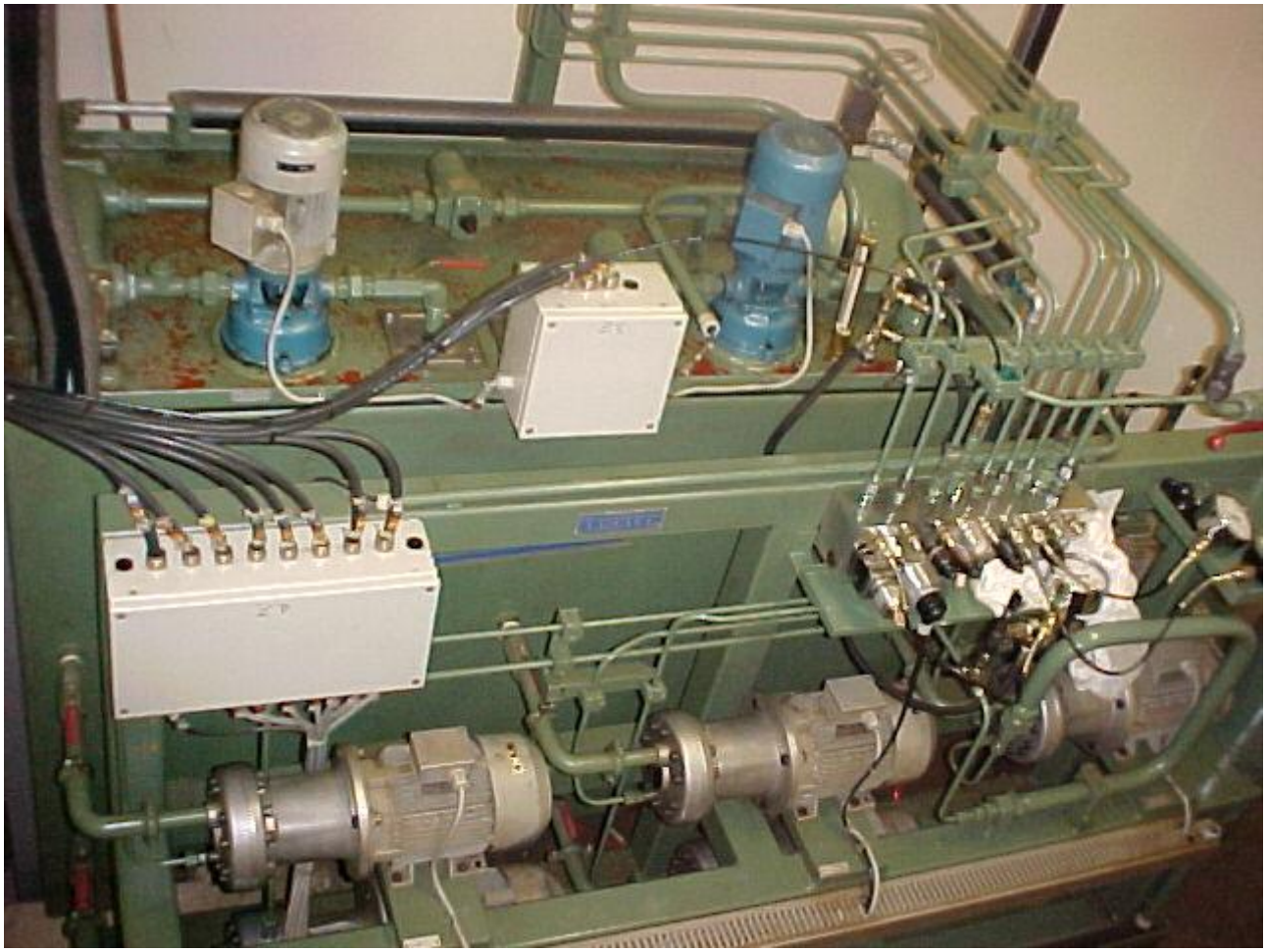


Figure 11 – Existing Hydraulic Power Pack

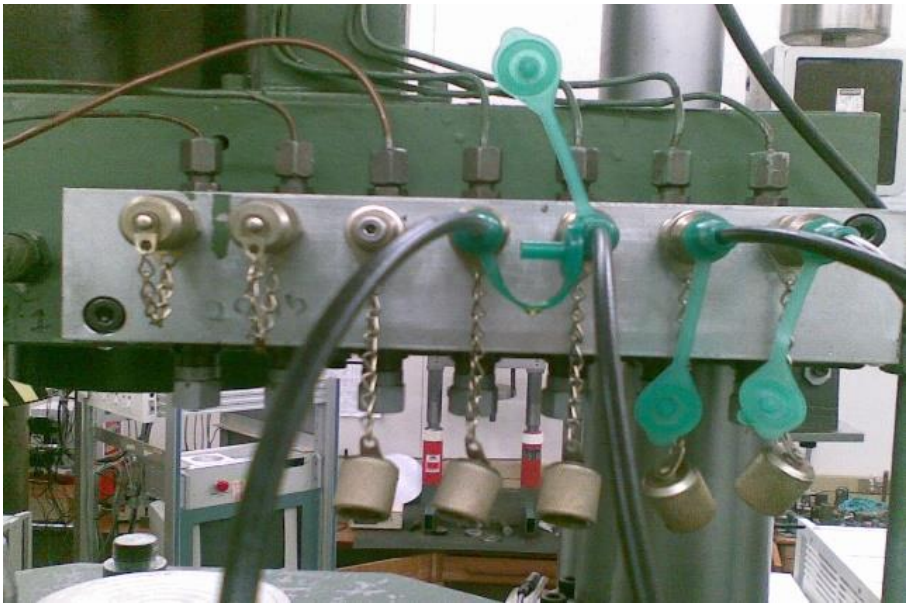


Figure 12 - hydrostatic bearing feed valve (1MN)

Figure 13 - hydrostatic bearing feed valve (200 kN)